Nonlinear Systems Theory

Homework #2 (2008) -- Answer

Question: How does the Wiener representation depend on input power?

Recall that for a linear-nonlinear-linear sandwich L_1NL_2 , where N is characterized by an input-output relationship f, the nth Wiener kernel is given by

$$K_{n}(t_{1},t_{2},...,t_{n}) = c_{n} \int L_{1}(t_{1}-\tau)L_{1}(t_{2}-\tau)...L_{1}(t_{n}-\tau)L_{2}(\tau)d\tau, \text{ where } c_{n} \text{ is the nth coefficient}$$

in the orthogonal expansion of f with respect to Hermite polynomials based on a Gaussian whose variance P is the variance of the signal that emerges from L_1 That is,

$$c_n = \frac{1}{n!P^n} \int_{-\infty}^{\infty} f(x)h_n(x;P)Gau(x,P)dx, \text{ where } Gau(x,P) = \frac{1}{\sqrt{2\pi P}} e^{-x^2/2P} \text{ and the Hermite}$$

polynomials $h_n(x; P)$ have the generating function $\sum_{n=0}^{\infty} \frac{z^n}{n!} h_n(x; P) = e^{xz-z^2/2P}$. For example, $h_0 = 1$, $h_1(x; P) = x$, $h_2(x; P) = x^2 - P$, $h_3(x; P) = x^3 - 3Px$, $h_4(x; P) = x^4 - 6Px^2 + 3P^2$,

Given this setup, determine how c_n depends on the power in the input signal. In particular, show that

$$\frac{\partial c_n}{\partial P} = \frac{(n+2)(n+1)}{2} c_{n+2}.$$

Hint: It will be useful to rewrite the Hermite polynomials in a manner that explicitly recognizes how they scale with P, namely, $h_n(x;P) = P^{n/2}H_n(\frac{x}{\sqrt{P}})$, where

$$\sum_{n=0}^{\infty} \frac{z^n}{n!} H_n(u) = e^{uz - z^2/2}$$

Solution (and see important note at the end):

First, the form $h_n(x; P) = P^{n/2} H_n(\frac{x}{\sqrt{P}})$ is implied by (a) noting that as the Gaussian widens by a factor of \sqrt{P} , then so do the resulting orthogonal polynomials, and (b) requiring that the leading coefficient (of x^n) is 1.

So
$$c_n = \frac{1}{n!P^n} \int_{-\infty}^{\infty} f(x)h_n(x;P)Gau(x,P)dx = \frac{1}{n!P^{(n+1)/2}\sqrt{2\pi}} \int_{-\infty}^{\infty} f(x)H_n(\frac{x}{\sqrt{P}})e^{-x^2/2P}dx$$
 and

$$\frac{\partial c_n}{\partial P} = -\left(\frac{n+1}{2}\right) \frac{1}{n! P^{(n+3)/2} \sqrt{2\pi}} \int_{-\infty}^{\infty} f(x) H_n(\frac{x}{\sqrt{P}}) e^{-x^2/2P} dx$$
$$+ \frac{1}{n! P^{(n+1)/2} \sqrt{2\pi}} \int_{-\infty}^{\infty} f(x) \left(-\frac{x}{2P^{3/2}} H_n'(\frac{x}{\sqrt{P}}) + \frac{x^2}{2P^2} H_n(\frac{x}{\sqrt{P}})\right) e^{-x^2/2P} dx,$$

where the first term comes from differentiating the factor in front of the integral, and the second term comes from differentiating the integrand. This reduces to

$$\frac{\partial c_n}{\partial P} = \frac{1}{2} \frac{1}{n! P^{(n+3)/2} \sqrt{2\pi}} \int_{-\infty}^{\infty} f(x) \Big(-(n+1)H_n(u) - uH_n'(u) + u^2 H_n(u) \Big) e^{-x^2/2P} dx , \qquad (1)$$

where $u = \frac{x}{\sqrt{P}}$. Below we will show that $H_{n+2}(u) = -(n+1)H_n(u) - uH'_n(u) + u^2H_n(u)$. (2)

Using this, eq. (1) becomes

$$\frac{\partial c_n}{\partial P} = \frac{1}{2} \frac{1}{n! P^{(n+3)/2} \sqrt{2\pi}} \int_{-\infty}^{\infty} f(x) H_{n+2}(u) e^{-x^2/2P} dx = \frac{1}{2} \frac{1}{n! P^{n/2+1}} \int_{-\infty}^{\infty} f(x) H_{n+2}(u) Gau(x; P) dx, (3)$$

or

$$\frac{\partial c_n}{\partial P} = \frac{1}{2} \frac{1}{n! P^{n+2}} \int_{-\infty}^{\infty} f(x) h_{n+2}(x; P) Gau(x; P) dx .$$
(4)

Since

$$c_{n+2} = \frac{1}{(n+2)!P^{n+2}} \int_{-\infty}^{\infty} f(x)h_{n+2}(x;P)Gau(x,P)dx, \text{ it follows that}$$
$$\frac{\partial c_n}{\partial P} = \frac{1}{2} \frac{(n+2)!}{n!} c_{n+2} = \frac{1}{2} (n+1)(n+2)c_{n+2}.$$
(5)

It remains to show eq. (2), which we will do by generating functions. The strategy is to find a generating function for the right-hand side of (2).

Starting with
$$\sum_{n=0}^{\infty} \frac{z^n}{n!} H_n(u) = G(u, z) = e^{uz - z^2/2}$$
, we find
 $\sum_{n=0}^{\infty} \frac{z^n}{n!} n H_n(u) = \sum_{n=1}^{\infty} \frac{z^n}{(n-1)!} H_n(u) = z \sum_{n=1}^{\infty} \frac{z^{n-1}}{(n-1)!} H_n(u) = z \frac{\partial}{\partial z} G(u, z) = z(u-z)G(u, z)$
and
 $\sum_{n=0}^{\infty} \frac{z^n}{n!} H_n'(u) = \frac{\partial}{\partial u} G(u, z) = zG(u, z)$
and so

$$\sum_{n=0}^{\infty} \frac{z^n}{n!} \Big(-(n+1)H_n - uH_n'(u) + u^2 H_n(u) \Big) = \Big(z(u-z) - 1 - uz + u^2 \Big) G(u,z)$$
(6)

$$= \left((u-z)^2 - 1 \right) G(u,z) = \frac{\partial^2}{\partial z^2} G(u,z) \,.$$

But

$$\frac{\partial^2}{\partial z^2} G(u,z) = \frac{\partial^2}{\partial z^2} \sum_{n=0}^{\infty} \frac{z^n}{n!} H_n(u) = \sum_{n=2}^{\infty} \frac{z^{n-2}}{(n-2)!} H_n(u) = \sum_{n=2}^{\infty} \frac{z^n}{n!} H_{n+2}(u).$$
(7)

Equating coefficients of z^n in (6) and (7) yields (2).

Note

The relationship

$$\frac{\partial c_n}{\partial P} = \frac{1}{2}(n+1)(n+2)c_{n+2} \tag{8}$$

has implications for nonlinear systems in general, because they are all linear combinations of LN-systems. For an LN-system,

 $K_n(t_1, t_2, ..., t_n) = c_n L_1(t_1) L_1(t_2) \cdot ... \cdot L_1(t_n)$. Since the *L*- factors are independent of the input power,

$$\frac{\partial}{\partial P} K_n(t_1, t_2, \dots, t_n) = \frac{(n+1)(n+2)}{2} c_{n+2} L_1(t_1) L_1(t_2) \cdot \dots \cdot L_1(t_n) .$$
But $K_{n+2}(t_1, t_2, \dots, t_n, t_{n+1}, t_{n+2}) = c_{n+2} L_1(t_1) L_1(t_2) \cdot \dots \cdot L_1(t_n) L_1(t_{n+1}) L_1(t_{n+2})$, so
$$(9)$$

$$c_{n+2}L_1(t_1)L_1(t_2)\cdot\ldots\cdot L_1(t_n)\int_0^\infty \left|L_1(t)\right|^2 dt = \int_0^\infty K_{n+2}(t_1,t_2,\ldots,t_n,t,t)dt \,.$$
(10)

In eq. (8), P is the power that gets past L_1 . So it is related to the input power P_{input} by

$$P = P_{input} \int_{0}^{\infty} |L_1(t)|^2 dt .$$
(11)

Combining (9), (10), and (11),

$$\frac{\partial}{\partial P_{input}} K_n(t_1, t_2, ..., t_n) = \frac{P}{P_{input}} \frac{\partial}{\partial P} K_n(t_1, t_2, ..., t_n) = \frac{(n+1)(n+2)}{2} \int_0^\infty K_{n+2}(t_1, t_2, ..., t_n, t, t) dt .$$
(12)

Since this is true for any LN-system, it is true for any sum of such systems.

Moreover, since the kernels are symmetric in their arguments, Eq. (12) can be interpreted as stating that the derivative of K_n with respect to input power is given by the integral of K_{n+2} over all diagonals in which two of its arguments are equal. There are exactly $\frac{(n+2)(n+1)}{2}$ such diagonals, accounting for the combinatorial factor in eq. (12).