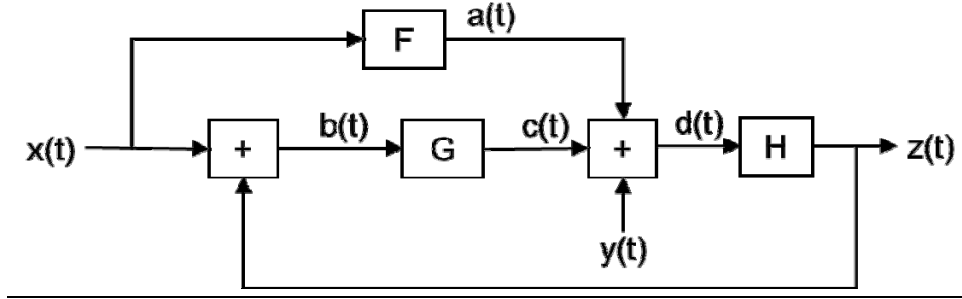


# Linear Systems, Black Boxes, and Beyond

## Homework #4 (2014-2015), Answers

### Q1: Covariances in a network

[Same set-up as Q1 of Homework 3] Given the following network, where  $F$ ,  $G$ , and  $H$  are linear filters with transfer functions  $\tilde{F}(\omega)$ ,  $\tilde{G}(\omega)$ , and  $\tilde{H}(\omega)$ , and  $x(t)$  and  $y(t)$  are independent noise inputs with power spectra  $P_x(\omega)$  and  $P_y(\omega)$ :



A. Calculate the cross-spectra  $P_{z,x}(\omega)$  and  $P_{z,y}(\omega)$ .

(Referring to last week's homework), we have  $\tilde{z}(\omega) = \tilde{K}(\omega) \left( (\tilde{F}(\omega) + \tilde{G}(\omega)) \tilde{x}(\omega) + \tilde{y}(\omega) \right)$ , where

$$\tilde{K}(\omega) = \frac{\tilde{H}(\omega)}{1 - \tilde{H}(\omega)\tilde{G}(\omega)}.$$

$P_{z,x}(\omega) = \lim_{T \rightarrow \infty} \frac{1}{T} \langle \tilde{z}(\omega) \overline{\tilde{x}(\omega)} \rangle = \lim_{T \rightarrow \infty} \frac{1}{T} \langle \tilde{K}(\omega) \left( (\tilde{F}(\omega) + \tilde{G}(\omega)) \tilde{x}(\omega) + \tilde{y}(\omega) \right) \overline{\tilde{x}(\omega)} \rangle$ . Since  $x(t)$  and  $y(t)$  are independent,  $\langle \tilde{y}(\omega) \overline{\tilde{x}(\omega)} \rangle = 0$ , so

$$\begin{aligned} P_{z,x}(\omega) &= \lim_{T \rightarrow \infty} \frac{1}{T} \langle \tilde{K}(\omega) (\tilde{F}(\omega) + \tilde{G}(\omega)) \tilde{x}(\omega) \overline{\tilde{x}(\omega)} \rangle \\ &= \lim_{T \rightarrow \infty} \frac{1}{T} \tilde{K}(\omega) (\tilde{F}(\omega) + \tilde{G}(\omega)) \langle \tilde{x}(\omega) \overline{\tilde{x}(\omega)} \rangle \\ &= \tilde{K}(\omega) (\tilde{F}(\omega) + \tilde{G}(\omega)) P_x(\omega) \end{aligned}$$

Similarly,

$$P_{z,y}(\omega) = \lim_{T \rightarrow \infty} \frac{1}{T} \langle \tilde{z}(\omega) \overline{\tilde{y}(\omega)} \rangle = \lim_{T \rightarrow \infty} \frac{1}{T} \langle \tilde{K}(\omega) \left( (\tilde{F}(\omega) + \tilde{G}(\omega)) \tilde{x}(\omega) + \tilde{y}(\omega) \right) \overline{\tilde{y}(\omega)} \rangle$$
. Again using  $\langle \tilde{y}(\omega) \overline{\tilde{x}(\omega)} \rangle = 0$ ,

$$P_{z,y}(\omega) = \lim_{T \rightarrow \infty} \frac{1}{T} \langle \tilde{z}(\omega) \overline{\tilde{y}(\omega)} \rangle = \lim_{T \rightarrow \infty} \frac{1}{T} \langle \tilde{K}(\omega) \tilde{y}(\omega) \overline{\tilde{y}(\omega)} \rangle = \tilde{K}(\omega) \lim_{T \rightarrow \infty} \frac{1}{T} \langle \tilde{y}(\omega) \overline{\tilde{y}(\omega)} \rangle = \tilde{K}(\omega) P_y(\omega).$$

B. Now assume that  $x(t)$  and  $y(t)$  are NOT independent, and their dependence is characterized by a nonzero cross-spectrum  $P_{x,y}(\omega)$ . Calculate the power spectrum  $P_z(\omega)$  in terms of  $P_x(\omega)$ ,  $P_y(\omega)$ , and  $P_{x,y}(\omega)$ .

We want to find  $P_z(\omega) = \lim_{T \rightarrow \infty} \frac{1}{T} \langle |\tilde{z}(\omega)|^2 \rangle = \lim_{T \rightarrow \infty} \frac{1}{T} \langle \tilde{z}(\omega) \overline{\tilde{z}(\omega)} \rangle$  Again using

$$\tilde{z}(\omega) = \tilde{K}(\omega) \left( (\tilde{F}(\omega) + \tilde{G}(\omega)) \tilde{x}(\omega) + \tilde{y}(\omega) \right),$$

$$\begin{aligned}
\langle \tilde{z}(\omega) \overline{\tilde{z}(\omega)} \rangle &= \left\langle \tilde{K}(\omega) \left( (\tilde{F}(\omega) + \tilde{G}(\omega)) \tilde{x}(\omega) + \tilde{y}(\omega) \right) \overline{\tilde{K}(\omega) \left( (\tilde{F}(\omega) + \tilde{G}(\omega)) \tilde{x}(\omega) + \tilde{y}(\omega) \right)} \right\rangle \\
&= \tilde{K}(\omega) \overline{\tilde{K}(\omega)} \bullet \\
&\left\langle (\tilde{F}(\omega) + \tilde{G}(\omega)) \tilde{x}(\omega) \overline{(\tilde{F}(\omega) + \tilde{G}(\omega)) \tilde{x}(\omega)} + (\tilde{F}(\omega) + \tilde{G}(\omega)) \tilde{x}(\omega) \overline{\tilde{y}(\omega)} + \tilde{y}(\omega) \overline{(\tilde{F}(\omega) + \tilde{G}(\omega)) \tilde{x}(\omega)} + \tilde{y}(\omega) \overline{\tilde{y}(\omega)} \right\rangle \\
&= |\tilde{K}(\omega)|^2 \bullet \\
&\left\langle |\tilde{F}(\omega) + \tilde{G}(\omega)|^2 \tilde{x}(\omega) \overline{\tilde{x}(\omega)} + (\tilde{F}(\omega) + \tilde{G}(\omega)) \tilde{x}(\omega) \overline{\tilde{y}(\omega)} + \overline{(\tilde{F}(\omega) + \tilde{G}(\omega))} \tilde{y}(\omega) \overline{\tilde{x}(\omega)} + \tilde{y}(\omega) \overline{\tilde{y}(\omega)} \right\rangle
\end{aligned}$$

So

$$\begin{aligned}
P_Z(\omega) &= \lim_{T \rightarrow \infty} \frac{1}{T} \langle \tilde{z}(\omega) \overline{\tilde{z}(\omega)} \rangle \\
&= |\tilde{K}(\omega)|^2 \bullet \\
&\lim_{T \rightarrow \infty} \frac{1}{T} \left\langle |\tilde{F}(\omega) + \tilde{G}(\omega)|^2 \tilde{x}(\omega) \overline{\tilde{x}(\omega)} + (\tilde{F}(\omega) + \tilde{G}(\omega)) \tilde{x}(\omega) \overline{\tilde{y}(\omega)} + \overline{(\tilde{F}(\omega) + \tilde{G}(\omega))} \tilde{y}(\omega) \overline{\tilde{x}(\omega)} + \tilde{y}(\omega) \overline{\tilde{y}(\omega)} \right\rangle \\
&= |\tilde{K}(\omega)|^2 \left( |\tilde{F}(\omega) + \tilde{G}(\omega)|^2 P_X(\omega) + (\tilde{F}(\omega) + \tilde{G}(\omega)) P_{X,Y} + \overline{(\tilde{F}(\omega) + \tilde{G}(\omega))} P_{X,Y} + P_Y(\omega) \right)
\end{aligned}$$

## Q2. Multiple signals with common and private noise sources

Say there are  $N$  observed signals  $z_i(t)$ , each of which is the result of adding a common noise source  $x(t)$ , filtered by a linear filter  $F_i$ , to a private noise source  $y_i(t)$ , filtered by a linear filter  $G_i$ . All the noises  $x(t)$  and  $y_i(t)$  are assumed independent.

A. Determine the cross-spectra  $P_{z_i, z_j}$  in terms of the power spectra  $P_X$ ,  $P_{Y_i}$ , and the filter characteristics  $\tilde{F}_i$  and  $\tilde{G}_i$ .

The Fourier estimates  $\tilde{z}_i(\omega)$  are given by  $\tilde{z}_i(\omega) = \tilde{F}_i(\omega) \tilde{x}(\omega) + \tilde{G}_i(\omega) \tilde{y}_i(\omega)$ , so

$$\begin{aligned}
\langle \tilde{z}_i(\omega) \overline{\tilde{z}_j(\omega)} \rangle &= \left\langle (\tilde{F}_i(\omega) \tilde{x}(\omega) + \tilde{G}_i(\omega) \tilde{y}_i(\omega)) \overline{(\tilde{F}_j(\omega) \tilde{x}(\omega) + \tilde{G}_j(\omega) \tilde{y}_j(\omega))} \right\rangle. \text{ Using independence of all of the} \\
\text{noises, } \langle \tilde{z}_i(\omega) \overline{\tilde{z}_j(\omega)} \rangle &= \left\langle \tilde{F}_i(\omega) \tilde{x}(\omega) \overline{\tilde{F}_j(\omega) \tilde{x}(\omega)} \right\rangle = \tilde{F}_i(\omega) \overline{\tilde{F}_j(\omega)} \langle \tilde{x}(\omega) \overline{\tilde{x}(\omega)} \rangle.
\end{aligned}$$

So (for  $i \neq j$ ),

$$P_{z_i, z_j}(\omega) = \lim_{T \rightarrow \infty} \frac{1}{T} \langle \tilde{z}_i(\omega) \overline{\tilde{z}_j(\omega)} \rangle = \lim_{T \rightarrow \infty} \frac{1}{T} \tilde{F}_i(\omega) \overline{\tilde{F}_j(\omega)} \langle \tilde{x}(\omega) \overline{\tilde{x}(\omega)} \rangle = \tilde{F}_i(\omega) \overline{\tilde{F}_j(\omega)} P_X(\omega).$$

For  $i = j$ , the cross-terms involving  $y$  do not vanish, so

$$\begin{aligned}
P_{z_i, z_i}(\omega) &= \lim_{T \rightarrow \infty} \frac{1}{T} \langle \tilde{z}_i(\omega) \overline{\tilde{z}_i(\omega)} \rangle = \lim_{T \rightarrow \infty} \frac{1}{T} \left( \tilde{F}_i(\omega) \overline{\tilde{F}_i(\omega)} \langle \tilde{x}(\omega) \overline{\tilde{x}(\omega)} \rangle + \tilde{G}_i(\omega) \overline{\tilde{G}_i(\omega)} \langle \tilde{y}_i(\omega) \overline{\tilde{y}_i(\omega)} \rangle \right) \\
&= |\tilde{F}_i(\omega)|^2 P_X(\omega) + |\tilde{G}_i(\omega)|^2 P_{Y_i}(\omega)
\end{aligned}$$

B. Now assume that all of the private noises  $y_i(t)$  are 0. Consider, for each frequency  $\omega$ , the matrix  $P_{z_i, z_j}(\omega)$ . Does it have any special properties?

It has only one nonzero eigenvalue. To see this, note that  $P_{Z_i, Z_j}(\omega) = \tilde{F}_i(\omega) \overline{\tilde{F}_j(\omega)} P_X(\omega)$ , even if  $i = j$ . So the rows of  $P_{Z_i, Z_j}(\omega)$  are all common multiples of each other. (The same holds for columns). That is,  $P_{Z_i, Z_j}(\omega)$  is the product of a column matrix, consisting of the  $\tilde{F}_i(\omega)$ , and a row matrix, consisting of the  $\overline{\tilde{F}_j(\omega)}$ , and the constant factor  $P_X$ . So, as a linear transformation, its range is a one-dimensional space, so it can have at most one nonzero eigenvector.

The corresponding eigenvalue is the trace of  $P_{Z_i, Z_j}(\omega)$  (since the trace is always the sum of the eigenvalues).

$$\text{tr}\left(P_{Z_i, Z_j}(\omega)\right) = \sum_i P_{Z_i, Z_i}(\omega) = P_X(\omega) \sum_i |\tilde{F}_i(\omega)|^2.$$

Note: the “global coherence” is defined as the ratio of the largest eigenvalue of the cross-spectral matrix  $P_{Z_i, Z_j}(\omega)$  to its trace. In the scenario in which all signals have a shared noise (and no private noise sources), we have just shown that the global coherence is 1.