

Linear Transformations and Group Representations

Homework #1 (2016-2017), Answers

Q1: Another mapping from a group (the rotations of a circle) into linear operators. Here, V is a two-dimensional vector space.

A. Find the eigenvalues of the transformation

$$R_\theta = \begin{pmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{pmatrix}.$$

Find the the characteristic equation:

$$\det(zI - R) = \det \begin{pmatrix} z - \cos \theta & -\sin \theta \\ \sin \theta & z - \cos \theta \end{pmatrix} = (z - \cos \theta)(z - \cos \theta) - (-\sin \theta)(\sin \theta)$$

$$= z^2 - 2z \cos \theta + \cos^2 \theta + \sin^2 \theta$$

$$= z^2 - 2z \cos \theta + 1$$

The eigenvalues are the roots of the characteristic equation, which we find by the quadratic formula:

$$\lambda = \frac{2 \cos \theta \pm \sqrt{4 \cos^2 \theta - 4}}{2}$$

$$= \cos \theta \pm \sqrt{\cos^2 \theta - 1}$$

$$= \cos \theta \pm \sqrt{-\sin^2 \theta}$$

$$= \cos \theta \pm i \sin \theta$$

$$= e^{\pm i\theta}$$

So there are two eigenvalues, $e^{i\theta}$ and $e^{-i\theta}$.

B. Find its eigenvectors.

We seek vectors $\vec{x} = \begin{pmatrix} u \\ v \end{pmatrix}$ for which $R\vec{x} = e^{i\theta}\vec{x}$ (and also, $R\vec{x} = e^{-i\theta}\vec{x}$). Looking just at the

eigenvalue $e^{i\theta}$,

$$R\vec{x} = e^{i\theta}\vec{x} \text{ implies } \begin{pmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{pmatrix} \begin{pmatrix} u \\ v \end{pmatrix} = e^{i\theta} \begin{pmatrix} u \\ v \end{pmatrix}, \text{ i.e.,}$$

$u \cos \theta + v \sin \theta = e^{i\theta}u$ and $-u \sin \theta + v \cos \theta = e^{i\theta}v$. Using $e^{i\theta} = \cos \theta + i \sin \theta$, the first equation is equivalent to $u \cos \theta + v \sin \theta = u \cos \theta + iu \sin \theta$, i.e., $v = iu$, and the second equation is equivalent to $-u \sin \theta + v \cos \theta = v \cos \theta + iv \sin \theta$, i.e., $-u = iv$. So both equations solve with

$v = iu$, i.e., the eigenvector is $\vec{x}_+ = \begin{pmatrix} 1 \\ i \end{pmatrix}$ (and any multiple of it).

Similarly, for the eigenvalue $e^{-i\theta}$, the eigenvector is $\vec{x}_- = \begin{pmatrix} 1 \\ -i \end{pmatrix}$ (and any multiple of it).

C. Since all of the transformations R_θ have the same eigenvectors (as shown in part B), they should commute. That is, $R_\theta R_\varphi = R_\varphi R_\theta$. Verify this.

$$\begin{aligned} R_\theta R_\varphi &= \begin{pmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{pmatrix} \begin{pmatrix} \cos \varphi & \sin \varphi \\ -\sin \varphi & \cos \varphi \end{pmatrix} \\ &= \begin{pmatrix} \cos \theta \cos \varphi - \sin \theta \sin \varphi & \cos \theta \sin \varphi + \sin \theta \cos \varphi \\ -\sin \theta \cos \varphi - \cos \theta \sin \varphi & -\sin \theta \sin \varphi + \cos \theta \cos \varphi \end{pmatrix} \\ &= \begin{pmatrix} \cos(\theta + \varphi) & \sin(\theta + \varphi) \\ -\sin(\theta + \varphi) & \cos(\theta + \varphi) \end{pmatrix} = R_{\theta + \varphi} \end{aligned}$$

Therefore, $R_\theta R_\varphi = R_{\theta + \varphi} = R_{\varphi + \theta} = R_\varphi R_\theta$, so we have shown that $R_\theta R_\varphi = R_\varphi R_\theta$.

Q2: Eigenvalues and eigenvectors in a function space. Here, V is the vector space of functions f on the real line. Consider the mapping H , defined by $Hf(x) = \frac{d^2 f}{dx^2}(x) - x^2 f(x)$.

A. Show that H is linear.

We need to show that H preserves addition and scalar multiplication. To show that H preserves addition:

$$\begin{aligned} H(f + g)(x) &= \frac{d^2}{dx^2}(f + g)(x) - x^2(f(x) + g(x)) \\ &= \frac{d^2 f}{dx^2}(x) + \frac{d^2 g}{dx^2}(x) - x^2 f(x) - x^2 g(x) \\ &= \frac{d^2 f}{dx^2}(x) - x^2 f(x) + \frac{d^2 g}{dx^2}(x) - x^2 g(x) \\ &= H(f)(x) + H(g)(x) \end{aligned}$$

To show that H preserves scalar multiplication:

$$H(\alpha f)(x) = \frac{d^2}{dx^2}(\alpha f)(x) - x^2 \alpha f(x) = \alpha \left(\frac{d^2 f}{dx^2}(x) - x^2 f(x) \right) = \alpha H(f)(x).$$

B. Show that $u_0(x) = e^{-x^2/2}$ is an eigenvector of H , and find its eigenvalue.

If $u_0(x) = e^{-x^2/2}$, then $\frac{d}{dx}u_0(x) = -xe^{-x^2/2}$, and $\frac{d^2}{dx^2}u_0(x) = \frac{d}{dx}(-xe^{-x^2/2}) = x^2e^{-x^2/2} - e^{-x^2/2}$. So

$$Hu_0(x) = \frac{d^2}{dx^2}u_0(x) - x^2u_0(x) = -e^{-x^2/2} = -u_0(x), \text{ so the eigenvalue is } -1.$$

C. Show that $u_1(x) = xe^{-x^2/2}$ is an eigenvector of H , and find its eigenvalue.

If $u_1(x) = xe^{-x^2/2}$, then $\frac{d}{dx}u_1(x) = -x^2e^{-x^2/2} + e^{-x^2/2}$, and

$$\frac{d^2}{dx^2}u_1(x) = \frac{d}{dx}(-x^2e^{-x^2/2} + e^{-x^2/2}) = x^3e^{-x^2/2} - 2xe^{-x^2/2} - xe^{-x^2/2} = x^3e^{-x^2/2} - 3xe^{-x^2/2}. \text{ So}$$

$$Hu_1(x) = \frac{d^2}{dx^2}u_1(x) - x^2u_1(x) = -3xe^{-x^2/2} = -3u_1(x), \text{ so the eigenvalue is } -3.$$

Q3. Eigenvalues of a permutation matrix. Say $M = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{pmatrix}$, so

$$M \begin{pmatrix} a \\ b \\ c \end{pmatrix} = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{pmatrix} \begin{pmatrix} a \\ b \\ c \end{pmatrix} = \begin{pmatrix} b \\ c \\ a \end{pmatrix}.$$

A. Show that $M^3 = I$.

$$M^3 \begin{pmatrix} a \\ b \\ c \end{pmatrix} = M^2 M \begin{pmatrix} a \\ b \\ c \end{pmatrix} = M^2 \begin{pmatrix} b \\ c \\ a \end{pmatrix} = MM \begin{pmatrix} b \\ c \\ a \end{pmatrix} = M \begin{pmatrix} c \\ a \\ b \end{pmatrix} = \begin{pmatrix} a \\ b \\ c \end{pmatrix}. \text{ (Or, we could just compute } M^3 \text{ by}$$

matrix multiplication.)

B. What are the eigenvalues of M ?

Say v is an eigenvector and λ is its eigenvalue. Then $M^3v = v$, since M^3 is the identity (by part A). But also, $M^3v = M^2(Mv) = M^2\lambda v = \lambda M^2v = (\lambda M)(Mv) = (\lambda M)(\lambda v) = \lambda^2 Mv = \lambda^3 v$. So $\lambda^3 v = v$, and $\lambda^3 = 1$.

So the three eigenvalues are the roots of $\lambda^3 = 1$, namely, 1 , $e^{\frac{2\pi i}{3}}$ and $e^{\frac{4\pi i}{3}}$.