

Linear Transformations and Group Representations

Homework #1 (2018-2019), Answers

Q1: Eigenvectors and eigenvalues of time-translation

A. Consider two vectors c_ω and s_ω defined by $c_\omega(t) = \cos(\omega t)$ and $s_\omega(t) = \sin(\omega t)$, and the vector space V_ω that they span. As before, define $(D_T v)(t) = v(t+T)$. Show that $D_T c_\omega$ and $D_T s_\omega$ are in V_ω by displaying $D_T c_\omega$ and $D_T s_\omega$ as linear combinations of c_ω and s_ω .

$$(D_T c_\omega)(t) = c_\omega(t+T) = \cos(\omega(t+T)) = \cos \omega T \cos \omega t - \sin \omega T \sin \omega t = (\cos \omega T) c_\omega(t) - (\sin \omega T) s_\omega(t)$$

so

$$D_T c_\omega = (\cos \omega T) c_\omega - (\sin \omega T) s_\omega.$$

Similarly,

$$(D_T s_\omega)(t) = s_\omega(t+T) = \sin(\omega(t+T)) = \sin \omega T \cos \omega t + \cos \omega T \sin \omega t = (\sin \omega T) c_\omega(t) + (\cos \omega T) s_\omega(t),$$

so

$$D_T s_\omega = (\sin \omega T) c_\omega + (\cos \omega T) s_\omega.$$

B. Express D_T as a 2×2 matrix, using c_ω and s_ω as a basis.

From Part A,

$$D_T c_\omega = (\cos \omega T) c_\omega - (\sin \omega T) s_\omega, \text{ so}$$

$$D_T s_\omega = (\sin \omega T) c_\omega + (\cos \omega T) s_\omega$$

$$D_T \begin{pmatrix} c_\omega \\ s_\omega \end{pmatrix} = \begin{pmatrix} \cos \omega T & -\sin \omega T \\ \sin \omega T & \cos \omega T \end{pmatrix} \begin{pmatrix} c_\omega \\ s_\omega \end{pmatrix}.$$

C. Write the characteristic equation for the 2×2 matrix in part B.

The characteristic equation for $D_T = \begin{pmatrix} \cos \omega T & -\sin \omega T \\ \sin \omega T & \cos \omega T \end{pmatrix}$ is $\det(zI - D_T) = 0$.

$$\det(zI - D_T) = \det \begin{pmatrix} z - \cos \omega T & \sin \omega T \\ -\sin \omega T & z - \cos \omega T \end{pmatrix} = (z - \cos \omega T)^2 - (\sin \omega T)(-\sin \omega T)$$

$$= z^2 - 2 \cos \omega T + (\cos \omega T)^2 + (\sin \omega T)^2, \text{ so the characteristic}$$

$$= z^2 - 2 \cos \omega T + 1$$

$$\text{equation is } z^2 - 2 \cos \omega T + 1 = 0.$$

D. Solve the characteristic equation in Part C to determine the eigenvalues of D_T in V_ω .

Using the quadratic formula, $z^2 - 2 \cos \omega T + 1 = 0$ solves for

$$z = \frac{2 \cos \omega T \pm \sqrt{4 \cos^2 \omega T - 4}}{2} = \cos \omega T \pm \sqrt{\cos^2 \omega T - 1} = \cos \omega T \pm i\sqrt{1 - \cos^2 \omega T}, \text{ where the last step is}$$

justified because $\cos^2 \omega T - 1 \leq 0$. So

$$z = \cos \omega T \pm i\sqrt{1 - \cos^2 \omega T} = \cos \omega T \pm i \sin \omega T = e^{\pm i\omega T}.$$

E. Show that $c_\omega \pm is_\omega$ are eigenvectors of D_T .

Using Part A,

$$D_T(c_\omega + is_\omega) = D_T(c_\omega) + iD_T(s_\omega) = ((\cos \omega T)c_\omega - (\sin \omega T)s_\omega) + i((\sin \omega T)c_\omega + (\cos \omega T)s_\omega).$$

Collecting terms,

$$((\cos \omega T)c_\omega - (\sin \omega T)s_\omega) + i((\sin \omega T)c_\omega + (\cos \omega T)s_\omega) =$$

$$(\cos \omega T + i \sin \omega T)c_\omega + (-\sin \omega T + i \cos \omega T)s_\omega =$$

$$(\cos \omega T + i \sin \omega T)c_\omega + (i \sin \omega T + \cos \omega T)is_\omega =$$

$$(\cos \omega T + i \sin \omega T)(c_\omega + is_\omega) = e^{i\omega T}(c_\omega + is_\omega)$$

So $D_T(c_\omega + is_\omega) = e^{i\omega T}(c_\omega + is_\omega)$, as required.

Similarly, $D_T(c_\omega - is_\omega) = e^{-i\omega T}(c_\omega - is_\omega)$. We didn't have to check this, since the assignment of i vs. $-i$ is arbitrary (i.e., complex-conjugation is an automorphism), and this switch leaves D_T invariant.

Q2: Eigenvectors and eigenvalues of the derivative

A. Setup is the same as Q1, but with the transformation Bv defined by $(Bv)(t) = v'(t)$, i.e., the derivative, rather than D_T . Display Bc_ω and Bs_ω as linear combinations of c_ω and s_ω .

$$(Bc_\omega)(t) = \frac{d}{dt}(\cos \omega t) = -\omega \sin \omega t = -\omega s_\omega(t).$$

$$(Bs_\omega)(t) = \frac{d}{dt}(\sin \omega t) = \cos \omega t = \omega c_\omega(t).$$

B. Express B as a 2×2 matrix, using c_ω and s_ω as a basis.

From Part A,

$$B \begin{pmatrix} c_\omega \\ s_\omega \end{pmatrix} = \begin{pmatrix} 0 & -\omega \\ \omega & 0 \end{pmatrix} \begin{pmatrix} c_\omega \\ s_\omega \end{pmatrix}.$$

C. Write the characteristic equation for the 2×2 matrix in part B.

The characteristic equation for $B = \begin{pmatrix} 0 & -\omega \\ \omega & 0 \end{pmatrix}$ is $\det(zI - B) = 0$.

$$\det(zI - B) = \det \begin{pmatrix} z & \omega \\ -\omega & z \end{pmatrix} = z^2 + \omega^2, \text{ so the characteristic equation is } z^2 + \omega^2 = 0.$$

D. Solve the characteristic equation in Part C to determine the eigenvalues of B in V_ω .

$$z^2 + \omega^2 = 0 \text{ solves for } z = \pm i\omega.$$

E. Show that $c_\omega \pm is_\omega$ are eigenvectors of B .

Using Part A, $B(c_\omega + is_\omega) = B(c_\omega) + iB(s_\omega) = (-\omega s_\omega) + i(\omega c_\omega) = i\omega(c_\omega + is_\omega)$.

So $B(c_\omega + is_\omega) = i\omega(c_\omega + is_\omega)$, as required. Similarly, $B(c_\omega - is_\omega) = -i\omega(c_\omega - is_\omega)$.