Motion and reverse-phi stimuli that do not drive standard Fourier or non-Fourier motion mechanisms

INTRODUCTION

Detection of motion is a crucial component of visual processing, and is generally considered to consist of two stages: an early stage in which local motion is extracted and a later stage at which local motion signals are combined into object motion or flows. Early motion processing is generally considered to be carried out by first-order (Fourier) and second-order (non-Fourier) mechanisms. Fourier motion mechanisms extract motion when the pairwise spatiotemporal correlation of luminance signal is present. Non-Fourier mechanisms are thought to work via local nonlinear pre-processing, such as flicker detection or extraction of unsigned contrast, followed by a spatiotemporal correlation of the resulting signals.

To probe the computations underlying motion perception, we created a new class of non-Fourier motion stimuli: binary movies characterized by their 3rd- and 4th-order spatiotemporal correlations. As with other non-Fourier stimuli, they lack second-order correlations, and therefore their motion cannot be detected by standard Fourier mechanisms. Additionally, these stimuli lack pairwise spatiotemporal correlation of edges or flicker – and thus, also cannot be detected by extraction of one of these features, followed by standard motion analysis.



STIMULUS CONSTRUCTION



Construction of a three-element spatiotemporal glider stimulus. The three-element glider (left) is represented by a wireframe cube with three of its corners colored. The three colored corners of the wireframe cube are the three voxels that form the glider. The coloring indicates the time steps occupied by each voxel: two voxels (green) are at time t, and one (blue) is at time t+1. The stimulus is constructed by applying an odd parity constraint to the number of black checks within all occurrences of the glider. The checks outlined in color in frame t and t+1 on the right illustrate this parity constraint for three placements of the glider. The red arrows show that, with in a glider, the color of a check in frame t+1 is determined by the color of other checks in frame t.



for the odd parity rule are on the right, except for the negative control, where only the even parity was tested. Fraction in centroid direction >0.6 or <0.4 is significant (p<0.05, two-tailed).

- Most stimuli (at least 16/23) were perceived having a definite direction of apparent motion.
- For 14 of the 16 stmuli for which there was a motion percept, the perceived direction of motion depended on the parity of the glider.
- For three-element gliders, reversal of parity is equivalent to reversal of contrast polarity – so this finding means that the apparent motion direction depends on contrast polarity.

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STIMULUS PROPERTIES

• Results are highly consistent across all 5 subjects.

- STIMULI:

- Viewing: binocularly at 50 cm

SUBJECTS:

- N=5, 1 male, 4 females
- Normal acuity or corrected to at least 20/30

TASK: Identify the direction of motion (2-alternative forced choice, left or right), respond with keypress.

The Centroid Direction



The centroid direction is defined as the vector from the centroid of the voxels at time t (open green circle), to the centroid of the voxels at time t+1 (open blue circle).

The centroid direction is the reference direction in the psychophysical experiment.





Combining opponent mechanisms

- perceptual data.
- ceptual data.
- of the glider, which is not very physiologic.
- correlations.
- reversing the contrast polarity.

METHODS

• 20-frame movie played at 10 fps (2 sec duration) Each frame is a 64x64 black-and-white checkerboard • Size: 25 degree square (each check: 24 min)

• Display: 17" LCD monitor at 60Hz, dim background.

CONDITIONS:

•Free view, binocular, self-paced •10 sets of stimuli generated with 3element gliders and 14 sets of stimuli generated with 4-element gliders •Each glider tested with 100 examples of each parity (even and odd) except for the negative control (even parity only). Stimuli with different gliders were intermixed in blocks. Results are pooled across eight sessions of one hour each (~5000 trials/subject).

MODELING

Motion signals generated by heterogeneous feature correlations

A four-element glider produces a correlation between an edge in one location and flicker in another location at a separate time.



three-element glider produces a correlation between an edge in one location and the luminance in another location at a separate time.

Motion signals generated by opponent mechanisms based on summation followed by a nonlinearity

| | R | nonlinearities | three-element gliders | | four-element gliders | |
|--|--------------------------------------|---|-----------------------|-------|----------------------|-------|
| | | | even | odd | even | odd |
| | | X | 0 | 0 | 0 | 0 |
| | | x^2 | 0 | 0 | 0 | 0 |
| | Summing luminances within the glider | x^3 | -0.44 | 0.44 | 0 | 0 |
| | | x^4 | 0 | 0 | 0.26 | -0.26 |
| | | | 0 | 0 | -0.25 | 0.25 |
| | Applying a nonlinearity | $\begin{cases} x , x \ge 0\\ 0, x < 0 \end{cases}$ | 0 | 0 | -0.18 | 0.18 |
| | | $\begin{cases} x^2, x \ge 0\\ 0, x < 0 \end{cases}$ | -0.23 | 0.23 | 0 | 0 |
| | | $\begin{cases} x ^{0.72}, x \ge 0\\ -0.08 x ^{0.72}, x < 0 \end{cases}$ | 0.11 | -0.11 | -0.21 | 0.21 |

Entries in the table are normalized size of the motion signal. Positive values mean that the net average signal is in the centroid direction, negative values means that it is opposite to the centroid direction. Zero means that no motion signal is generated.

These models generate a motion signal but...

1. Predicted motion direction has a fixed relationship to the centroid motion of each glider, but this is not true in the

2. Reversing the parity of the glider rule always results in a reversal of motion direction, but this is not true in the per-

3. Both models only generate a strong motion signal when the summing area has the same spatiotemporal shape

SUMMARY

1. We observed consistent motion percepts with stimuli created using 3rd and 4th order spatiotemporal

2. The direction of perceived motion can change by changing the parity rule of the gliders that generate the stimuli, without changing the spatiotemporal configuration of the gliders themselves.

3. For three-element glider stimuli, this means that the perceived motion direction can be reversed by

4. Preliminary modeling only partially account for our results. These simple models can (at most) extract motion signal from the glider stimulus, but cannot correctly predict its direction and strength.