

## Linear Systems: Black Boxes and Beyond

### Homework #1 (2024-2025), Questions

#### Q1. Some important transfer functions

- A. The “boxcar”, which averages a signal  $s(t)$  over a previous interval  $\tau$ :

$$f(t) = \begin{cases} \frac{1}{\tau}, & 0 \leq t \leq \tau \\ 0, & \text{otherwise} \end{cases}. \text{ Compute the transfer function, } \hat{f}(\omega) = \int_{-\infty}^{\infty} e^{-i\omega t} f(t) dt.$$

- B. The delay, i.e., a filter for which the response to a signal  $s(t)$  is  $r(t) = s(t - \tau)$ , the impulse response is  $f(t) = \delta(t - \tau)$ . Compute the transfer function.

- C. Non-causal boxcar averaging, i.e., averaging a signal  $s(t)$  over the interval from  $-\tau/2$  to  $+\tau/2$ . Compute the transfer function.

- D. The derivative, method 1: Consider a filter  $f$  whose output is the time-derivative of the input. First, for any signal  $s(t)$ .  $s'(t) = \lim_{\tau \rightarrow 0} \frac{s(t) - s(t - \tau)}{\tau}$ . Say  $f_{\tau}$  yields

$$\frac{s(t) - s(t - \tau)}{\tau}. \text{ Using part B, determine } \hat{f}_{\tau}(\omega) \text{ and then } \hat{f}(\omega) = \lim_{\tau \rightarrow 0} \hat{f}_{\tau}(\omega).$$

- E. The derivative, method 2: If  $r(t) = s'(t)$ ,  $\hat{r}(\omega)$  can be directly determined from  $\hat{s}(\omega)$ , by expressing  $s(t)$  in terms of  $\hat{s}(\omega)$  and then differentiating.

- F. From either D or E, what is the transfer function  $\hat{f}_n(\omega)$  corresponding to the  $n$ th derivative?

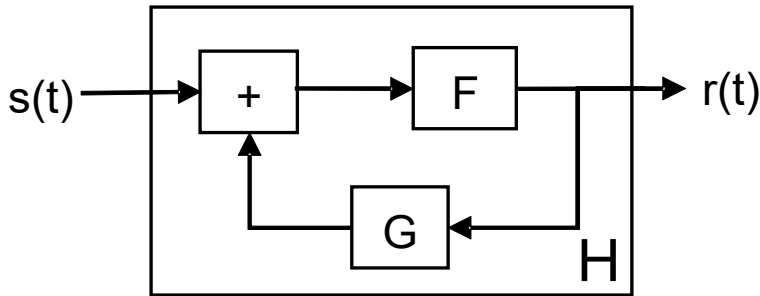
$$\hat{f}_n(\omega) = \left( \hat{f}_1(\omega) \right)^n, \text{ where } \hat{f}_1(\omega) \text{ is the first-derivative transfer function of part D or E. So}$$

$$\hat{f}_n(\omega) = \left( \hat{f}_1(\omega) \right)^n = (i\omega)^n.$$

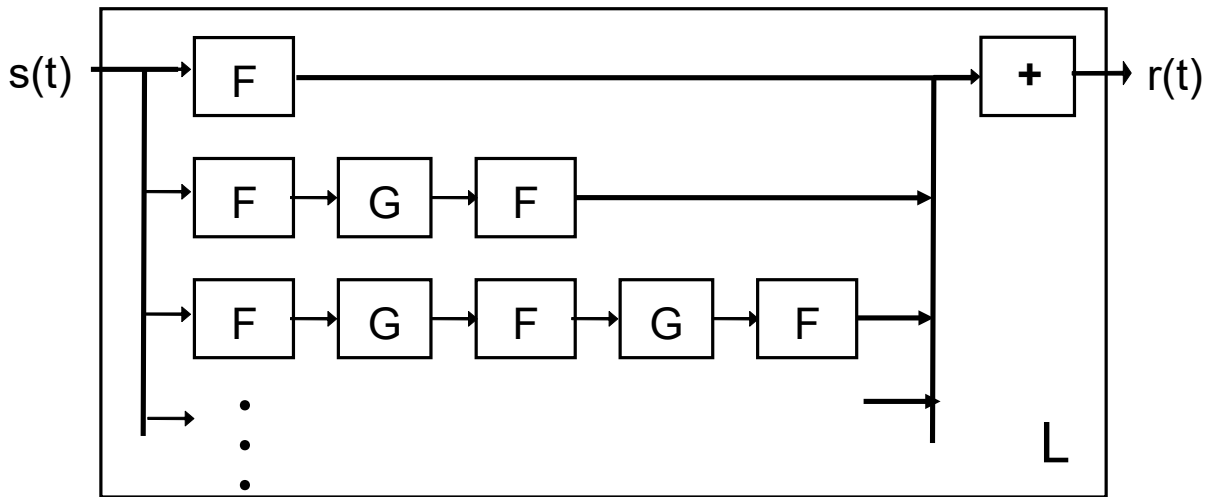
#### Q2. Feedback and feedforward

We had determined the transfer function of the composite system  $H$  diagrammed here (worked out in class with the feedback signal multiplied by an arbitrary amount  $k$ ; here, for simplicity,

with  $k = 1$ ). For this system,  $\hat{h}(\omega) = \frac{\hat{f}(\omega)}{1 - \hat{f}(\omega)\hat{g}(\omega)}$ .



Now, consider the following system, of parallel feedforward elements:



What is its transfer function,  $\hat{l}(\omega)$ ? How does it compare to  $\hat{h}(\omega)$ ?

Q3. The Fourier transform of a Gaussian.

We evaluate  $J(D,u) = \int_{-\infty}^{\infty} e^{-\omega^2 D/2} e^{i\omega u} d\omega$ .

A. First, consider  $I(V) = \int_{-\infty}^{\infty} e^{-x^2/2V} dx$ , the integral of a non-normalized Gaussian. Note that

$I^2$  can be considered a two-dimensional integral (say, in  $x$  and  $y$ ), and also an integral in polar coordinates with  $r^2 = x^2 + y^2$ . In polar coordinates, the integral is straightforward. This yields  $I^2$  and hence  $I$ .

$$I^2 = \int_{-\infty}^{\infty} e^{-x^2/2V} dx \int_{-\infty}^{\infty} e^{-y^2/2V} dy = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} e^{-x^2/2V} e^{-y^2/2V} dx dy = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} e^{-(x^2+y^2)/2V} dx dy.$$

Changing to polar coordinates, with  $dx dy = r dr d\theta$ :

$$I^2 = \int_0^{\infty} \int_0^{2\pi} e^{-r^2/2V} r dr d\theta = 2\pi \int_0^{\infty} e^{-r^2/2V} r dr. \text{ With } t = r^2/2, dt = r dr, \text{ and}$$

$$I^2 = 2\pi \int_0^{\infty} e^{-t/V} dt = -2\pi V (e^{-t/V}) \Big|_0^{\infty} = 2\pi V. \text{ So } I = \sqrt{2\pi V}.$$

B. Evaluate  $\int_{-\infty}^{\infty} e^{-\omega^2 D/2} e^{i\omega u} d\omega$  by completing the square in the exponent.